

並行分散計算特論 (14)

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Logical Characterization

- Linear Temporal Logic
 - Specification for the computation path
 - Property description for a sequence of transitions
- Branching Temporal Logic
 - Specification for the computation tree
 - Property description for all possible tree of transitions

LTL states the properties about a path:

A state that satisfies p is always followed by a states that satisfies q

BTL sates the properties about branches:

All transitions from a state that satisfies p lead to the states that satisfy q

Propositional Temporal Logic

$$F ::= p \mid \neg F \mid F \wedge F \mid \bigcirc F \mid FUF$$

Temporal operators

$\bigcirc\phi$: ϕ holds after the next transition.

$\phi_1\mathcal{U}\phi_2$: ϕ_1 holds until ϕ_2 holds.

$$\sigma \models p \text{ iff } p \in \sigma^0$$

$$\sigma \models \neg\phi \text{ iff } \sigma \not\models \phi$$

$$\sigma \models \phi_1 \wedge \phi_2 \text{ iff } \sigma \models \phi_1 \text{ and } \sigma \models \phi_2$$

$$\sigma \models \bigcirc\phi \text{ iff } \sigma^1 \models \phi$$

$$\sigma \models \phi_1\mathcal{U}\phi_2 \text{ iff } \text{For some } j \geq 0. \sigma^j \models \phi_2 \\ \text{and } \sigma^k \models \phi_1 \text{ for all } 0 \leq k < j$$

PTL specification

$$\diamond\phi \equiv \text{true } \mathcal{U}\phi \quad \square\phi \equiv \neg(\text{true } \mathcal{U}\neg\phi)$$

$$\square(p \rightarrow \diamond q) : \text{state } p \text{ is always followed by state } q.$$

Satisfiability of PTL-formulas is checked in PSPACE-complete.

Model: Kripke structure $M = \langle S, S_0, \mu, E \rangle$

S : States

$S_0 \subseteq S$: Initial states

μ : $S \rightarrow 2^{AP}$

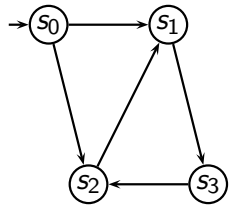
$E \subseteq S \times S$: Transitions

Check: Check if path(s) of M satisfy property ϕ .

Usually the paths beginning from an initial state.

Timed PTL

With specification when a transition may occur



$\rho: (S_0, l_0) \rightarrow (S_1, l_1) \rightarrow (S_2, l_2) \rightarrow \dots$
 l_i : interval l_i is adjacent to l_{i+1}

Interval: $[a, b], [a, b), [a, \infty), (a, b], (a, b), (a, \infty)$
 $[,]$ for closed intervals, $(,)$ for open intervals

notation: ρ^t : State sequence after time t .

$t \in l_i, \rho^t = (\sigma_i, l_i - t) \rightarrow (\sigma_{i+1}, l_{i+1} - t) \rightarrow \dots$

MITL(metric interval temporal logic)[Alur90]

MITL formula

$F ::= p \mid \neg F \mid F \wedge F \mid F \mathcal{U}_I F$

MITL semantics $\rho = (\bar{\sigma}, \bar{I})$: timed state sequence.

$\rho \models p$ iff $p \in \sigma^0$

$\rho \models \neg \phi$ iff $\rho \not\models \phi$

$\rho \models \phi_1 \wedge \phi_2$ iff $\rho \models \phi_1$ and $\rho \models \phi_2$

$\rho \models \phi_1 \mathcal{U}_I \phi_2$ iff for some $t \in I, \sigma^t \models \phi_2$
 $\sigma^{t'} \models$ for all $t' \in (0, t)$

Derived operators

$\diamond_I \phi \equiv \text{true } \mathcal{U}_I \phi$ $\square_I \phi \equiv \neg \diamond_I \neg \phi$
 $\phi_1 \text{ unless } \phi_2 \equiv \neg((\neg \phi_2) \mathcal{U}_I (\neg \phi_1))$ $\phi_1 \text{ unless } \phi_2$

What do these formulas mean?

$p \wedge \square_{\geq 0}(p \rightarrow (\neg) \mathcal{U}_{(0, \infty)} p)$.

$\square_{(0, \infty)}(p \rightarrow \diamond_{[0, 3]} q)$.

Rational time satisfiability

Definition

$(\bar{\sigma}, \bar{I})$ is rational if the end-points of all intervals in \bar{I} are rational.

ρ \mathcal{Q} -satisfies ϕ iff $\rho \models_{\mathcal{Q}} \phi$ where all time variables range over only \mathcal{Q}

A MITL formula ϕ is \mathcal{Q} -satisfiable iff it is satisfiable.

Undecidability[Alur90]

Proposition

If singular intervals are allowed as subscripts for temporal operators in MITL, then the satisfiability problem is undecidable.

Singular interval: $[a, a]$

If no singular interval is allowed,

- $\Box(p \rightarrow \Diamond_{=5} q)$ is not in MITL
- $\Box(p \rightarrow (\neg q) \mathcal{U}_{=5} q)$ is in MITL

Satisfiability

Theorem

The satisfiability of MITL (with no singular interval) is EXPSPACE-complete.

Alur's algorithm: $O(2^{N \cdot K \cdot \log(N \cdot K)})$

- K : largest integer constant in $\phi + 1$
- N : number of propositions, boolean connectives and temporal operators in ϕ .

Model checking TA with MITL

For a timed automaton A , check if $L_{\mathcal{T}}(A) \subseteq L(\phi)$

Construct a TA that accepts $L(A) \cap L(B_{\neg\phi})$ and check its emptiness.

Construction of $A \times B_{\neg\phi}$ is exponential for $|\phi|$. Checking emptiness is PSPACE-complete.

A minor extension for timed automata to deal with intervals.

More on Timed Automata

Timed Safety Automata[Henzinger94]

Timed automata with state invariants.

State invariants: time constraints on states

All states are Büchi accepting.

Effective in checking safety properties. All safety properties can be checked in the finite prefix.

Zone construction[BengtssonYi04]

More efficient than regions Symbolic timed model checking.

Regions \Rightarrow Zones (difference constrains)

Bounded Difference Matrix(BDM): Efficient data structure

Uppaal incorporates these effective verification method.[BengtssonYi04]

Other timed model

Timed I/O automata [Kaynar, Lynch, Segara, Vaandrager05]

Process calculi with time

- Realtime ACP [Baeten91]
- Timed CCS [Yi90]
- Timed CSP [Schneider00]
- ATP [Nicolin, Sifaxis90]
- TPL [Regan, Hennessy95]

SOS characterization with time

OSOS with time tick [UlidowskiYuen04]

Summary

- Concurrent computation model
A set of automata with synchronization
- Process calculus(CCS)
Algebraic characterization based on bisimulations
- Timed extension
Time as a synchronization measure
A theory of timed automaton and its extension

Await for time-aware application.